

# Observation Centric and Central Distance Recovery on Sports Player Tracking

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**Abstract.** Multi-Object Tracking over humans has improved rapidly with the development of the object detection and re-identification. However, multi-actor tracking over humans with similar appearance and non-linear movement can still be very challenging even for the state-of-the-art tracking algorithm. Current motion based tracking algorithm often use Kalman Filter to predict the motion of object, however, its linear movement assumption can cause failure in tracking when the target is not moving linearly. And for multi-players tracking over the sports field, because the players in the same team are usually wearing the same color of jersey, making re-identification even harder both in the short term and long term in the tracking process. In this work, we proposed a motion based tracking algorithm and three ReID post-processing pipelines for three sports including basketball, football and volleyball, we successfully handle the tracking of non-linear movement of players on the sport fields. Experiments result on the testing set of ECCV DeeperAction Challenge SportsMOT Dataset demonstrates the effectiveness of our method, which achieves HOTA of 73.968, ranking 3rd place on the 2022 Sportsmot workshop final leaderboard.

**Keywords:** Multi-object Tracking, Occlusion, ReID, Association

## 1 Introduction

Multi-object tracking is a fundamental task in computer vision, aiming to associate objects bounding boxes and keep track of all the identities in video sequences. Most of the multi-object tracking datasets mainly focus on pedestrians in crowded street scenes (e.g., MOT17/20) [1]. In these scenes, most of the pedestrians movement is slow and linear and thus easy to predict, besides that, the appearance of each identity is easy to distinguish, making the re-identification in the tracking process easier. However, there is a lack of multi-object tracking algorithm that can successfully handle the non-linear movement of sports players and the challenge of similar appearance between players on the sports field scenes. To this purpose, we introduced an observation-centric and central distance recovery tracking algorithm that can handles the non-linear movement of players on the sports field, and also use appearance ReID post-processing to deal with the fragment tracklets during tracking.

## 2 Related Works

### 2.1 Location and Motion Based Object Tracking

Modern object tracking algorithms usually follow the paradigm of tracking by detection. Several motion based tracking algorithms adopt the Kalman filter [2] to formulate the moving trajectories of the target with the detections from object detector. However, the linear assumptions of Kalman filter can fall short when the target is not moving in a linear way. Observation-Centric SORT [3] includes moving direction similarity between detection and tracklets into the Hungarian Algorithm [4] cost and reforming the trajectories of re-identify target to prevent error accumulations in the Kalman filter update process. These methods show effectiveness when dealing with the non-linear movements of objects, achieving state-of-the-art tracking performance on several multi-object tracking datasets.

### 2.2 Appearance Based Object Tracking

With the fast development in the appearance feature extractor, some tracking algorithms incorporate target appearance during association [5,6] and utilizes the appearance as a clue for identity recognition. However, most of these appearance cues based algorithms often fall short in many cases especially when targets are occluded, when the scene is very crowded or the targets are sharing similar appearances.

## 3 Proposed Method

There are several challenges need to be tackled in the tracking of sports player. First, the non-linear movement of the players on the court. Given the high intensity in sports like volleyball, basketball and football, players need to sprint, jump and change directions in a short time during the game, causing the movement to be unpredictable. Second, the heavy occlusion problem during the game. The players will cluster together during the sports game when some particular situations happened like grabbing the rebound in basketball or blocking in volleyball. When this happened, it causes detection to be unreliable due to occlusion, and thus causes the tracking performance to drop if we do not take care the recovery of the tracklets with lost detection carefully. Third, in the sports video clips, a player can goes out and re-entry the camera view again after several seconds, when this happened, we need to re-identify the player with the correct identity. However, given the similar appearance between those team players within the same team, it is difficult to re-identify them correctly by using their appearance. In our work, we proposed several methods to deal with these three challenges.

### 3.1 Observation-Centric Tracking

The non-linear movement is causing big trouble during the tracking process. To tackle this problem, we use Observation-Centric SORT (OCSORT) as our main

tracking algorithm. Its Observation-centric Online Smoothing strategy helps deal with the non-linear movement of the target by rebuilding a virtual trajectory when a lost target is associated again after a period of being untracked, and thus prevent error accumulation in the Kalman filter. Also, because the players on the sports field can change moving direction in a short time, the Observation-Centric Momentum in OCSORT also helps reduce the tracking error caused by sudden direction change. Lastly, after the association stage is finished, OCSORT performs Observation-Centric Recovery, trying to associate the last observation of an unassociated track to the detections on the new-coming time step. This strategy helps to reduce the generation of a new tracklet, which is usually abnormal given the fixed number of players on the sports field.

### 3.2 Central Distance Recovery

After the association stage is done in OCSORT, there is still a chance that observation-centric recovery failed to successfully recover the identity of the targets and initiate a new tracklet. This is mainly due to observation-centric recovery is based on using bounding box IoU as the Hungarian assignment cost, while the unassociated tracklet and the unmatched detection sometimes does not necessarily share an overlapping region given the fast moving speed of sports player. To deal with this, we use the Euclidean distance between detections and the last observation of an unassociated tracks to conduct observation-centric recovery again, as this stage is based on bounding boxes' central distance, we call this process "central distance recovery".

### 3.3 Tracklets Association Post-Processing

After the tracking stage is finished, the result usually ended up in a bigger number in identities than the number of identities in the ground truth. This is because when a player re-entry the camera view, the tracking algorithm usually treat the player as a new identity and does not re-identify the player. To deal with the player re-entry problem, we incorporate different strategy in three sport scenes according to the number of sports player, size of the sports field and several other sport characteristics.

#### Post-Processing in Basketball

The total number of player in a basketball game is 10, we use this as a main constraint to conduct the post-processing. Due to the large amount of player's camera re-entry in basketball comparing to other sports, it is necessary to incorporate person re-identification in the post-processing stage. After we get the preliminary tracking result, we initiate the first 10 tracklets we get as the ten main players on the court. We keep updating the tracklets appearance feature using exponential moving average. Whenever a player leaves the camera view, we put the player's tracklet into a candidates queue. And whenever a new tracklet (player) enter the camera view, we associate the player to one of the tracklets in the candidates queue that shares the highest cosine similarity between both.

## Post-Processing in Football

The search space of candidates in football is much bigger comparing to other sports because of the bigger number of the players in a football game and a lower ratio of players inside the camera view to the total number of players. Thus it is necessary to incorporate the position as a constraint during re-id process. In football tracking, due to the uncertainty in number of identities in a video clip, we decided not to use the number of total players as a constraint, instead, we only try to associate fragment tracklets together based on their appearance similarity and entry/exit position. There is total of three rounds association based on appearance similarity and location between tracklets. The prerequisites for two tracklets to be associated together is first based on their disappear and reappear location. The threshold for the location distance for two tracklets to be associated is determined by the number of frames between a tracklet disappear and reappear in the camera view, which means that if a tracklet disappear and reappear in the camera view in a short amount of time, the distance threshold for their location will be small given the moving distance should not be far in such a short time, and vice versa for a longer disappearing time. After passing the threshold of location distance, we then try to compare the cosine similarity based on two tracklets' appearance. We calculate two tracklets' average frame-based embedding features distance as their final distance. If the final distance is smaller than the embedding threshold, we consider these two tracklets the same identity. We use three rounds of association based on different matching threshold of appearance similarity.

## Post-Processing in Volleyball

Comparing to basketball and football, volleyball player usually stays in the camera view throughout the entire video clip, and even they disappear, they reappear in a very close location. Due to the above reason, we do not incorporate appearance in the post-processing of volleyball. We use a similar strategy like basketball post-processing, we limited the number of tracklets to 12 players, and try to re-associate disappearing players to candidates only based on the distance of their disappear and reappear location.

## Interpolation

After the ReID post-processing part is done, we use linear interpolation as our last step to produce the final tracking results.

# 4 Experiments and Results

## 4.1 Datasets

We use the training sets from SportsMOT for detector and ReID model training. The training set contains 45 video clips from 3 categories (i.e., basketball, football and volleyball), where are collected from Olympic Games, NCAA Championship, and NBA games on YouTube. Only the search results with 720P

resolution, 25 FPS, and official recording are downloaded. All of the selected videos are cut into clips of average 485 frames manually, in which there is no shot change.

## 4.2 Implementation Details

### Detector

We use YOLOX [7] as our detector due to its high accuracy and fast inference speed. For the pretrained weight we use the COCO pretrained YOLOX-X model provided by the official GitHub repositories of YOLOX. We train the model with Sportsmot training set for 80 epoches, following the YOLOX-X default training process of ByteTrack’s [8] official GitHub repositories. The training duration takes around 8 hours on 4 tesla V100 gpu.

### Observation-Centric SORT

We keep the original configuration of OCSORT, using 0.1 detection confidence threshold, 0.3 IoU threshold, 0.7 track threshold and a maximum tracklet age of 30 frames for all of the sports.

### Central Distance Recovery

The central distance recovery threshold is different based on the sports type. We set basketball’s distance threshold as 200, football’s distance threshold as 80, and volleyball’s distance threshold as 80. The choosing of threshold is based on the evaluation performance on the Sportsmot testing set.

### Person ReID

We are using OSNet[9] as our backbone network for feature extraction. The model is trained with Sportsmot training set for 10 epochs, using Adam optimizer with 0.0003 learning rate.

### Basketball Post-Processing Setting

In the post-processing of basketball, we limited the number of tracklets to 10, just like the number of players on the court, unless more than 10 detections appear at the same time, we do not initiate new tracklets. The re-identification of player is based on their cosine similarity of their embedding features.

### Football Post-Processing Setting

In football, considering the ratio of players inside and outside the camera, we use the cosine similarity and also players’ position to conduct re-identification for camera re-entry players. There are three rounds of association stage. The association between two tracklets need to pass through a threshold of tracklet position distance before they have a chance to be associated. The distance threshold is based on their disappear and reappear time gap, for those tracklets that have a

time gap of less than 100 frames, the distance threshold is 100. For the tracklets that share a time gap between 100 to 500 frames, the distance threshold is 250, and for those tracklets that share a time gap bigger than 500 frames, the distance threshold is set to 400. In three rounds of association, we try to associate as many as tracklets we can in a greedy style. For the first round of association, if the cosine distance of two tracklets is smaller than 0.1, we treat them as the same identity and conduct association. For the second round, the cosine distance threshold is 0.2, and the third round is 0.4.

### **Volleyball Post-Processing Setting**

Due to the relatively low number of player camera re-entry case in volleyball comparing to basketball and football, the search space of re-entry player is small. So the post-processing of volleyball is simply based on their disappear and reappear position. For re-entry player, we select the player in the re-associate candidate who has the closest distance between the disappear position of candidates and reappear position of new player for re-identification if their distance is lower than a threshold of 400.

### **4.3 Evaluation Results**

The 2022 ECCV DeeperAction Challenge - SportsMOT Track on Multi-actor Tracking competition is ranked according to the HOTA [10] performance. In contrast to MOTA [11], HOTA maintains a balance between the accuracy of object detection and association. The original OCSORT has a performance of 67.107 in HOTA, after the incorporation of central-distance recovery, the HOTA improves to 71.764. After the ReID post-processing stage, we achieve 73.968 in HOTA, 63.460 in AssA, 86.316 in DetA, 94.832 in MOTA, 78.271 in IDF1, 2754 in IDS and 3592 in Frag, showing the effectiveness of our method.

## **5 Conclusions**

In this paper, we modify the motion based observation-centric SORT with an extra central distance recovery stage, improving the performance without adding to much computational cost and also keeps the algorithm online, successfully tackle down the challenges of non-linear movement during tracking. We also propose a ReID post-processing stage for each sports according to the sport characteristics. Our final performance achieve 73.968 in HOTA, ranking 3rd place among all of the teams in the 2022 ECCV DeeperAction Challenge - SportsMOT Track on Multi-actor Tracking.

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